

# SIEMENS

## SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link



Protection Systems  
Catalog  
SIPROTEC 5.2 · 1999



# C E R T I F I C A T E

**DQS Deutsche Gesellschaft zur Zertifizierung  
von Managementsystemen mbH**  
Qualitäts- und Umweltgutachter

hereby certifies that the company

**SIEMENS AG**  
**Power Transmission and Distribution Group (EV)**  
**Protection and Substation Control Systems (EV S)**

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Protection Relays, Substation Control  
Remote Terminal Units, Fault Recorders

has implemented and maintains a

**quality system.**

A quality audit, documented in an audit report, has verified  
that this quality system fulfils the requirements  
of the following standard

**DIN EN ISO 9001**  
August 1994 edition

This certificate is valid until 2001-09-04

Certificate Registration No. 876-03

Frankfurt am Main, Berlin 1996-07-08

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# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

- Differential protection relay for overhead lines and cables
  - Current differential protection with external summation current transformer 4AM49 (87L)
  - Suitable for use for distances of 12 km max. via two pilot-wires
  - Differential protection can be combined with overcurrent release
  - Pilot-wire monitoring function
  - Bidirectional remote tripping
  - Circuit-breaker intertripping at the remote station
  - Seal-in of the TRIP command until manual reset (Lockout function)
  - Minimal current transformer requirements due to integrated saturation detector
  - Restraint against inrush / undelayed trip for high differential fault currents
- Operational measured values
  - Local and remote current
  - Differential current
  - Restraint current
- Monitoring functions
  - Hardware
  - Firmware
  - Spill current supervision
- Hardware
  - Auxiliary supply voltages  
24, 48 V DC  
60, 110, 125 V DC  
220, 250 V DC, 115 V AC
  - Local operation by means of integrated keyboard
  - LCD display for settings and analysis
  - Housing  
flush-mounted housing 1/6  
19" 7XP20  
surface-mounted housing 1/6  
19" 7XP20



**Fig. 1**  
SIPROTEC 7SD60  
Numerical current  
differential protection relay

- Communication
  - via personal computer and DIGSI 3  
via RS232↔RS485 converter
  - with modem
  - with substation control system  
via IEC 60870-5-103
  - 2 kV isolated RS485 interface,  
bus connection possible
- Protection functions  
ANSI IEC
  - Ⓢ7L Ⓢ7T  $\Delta I$  for lines/cables,  
transformers
  - Ⓢ5 Intertrip, remote  
trip
  - Ⓢ6 Lockout function

## Differential protection

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# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Description

### Application

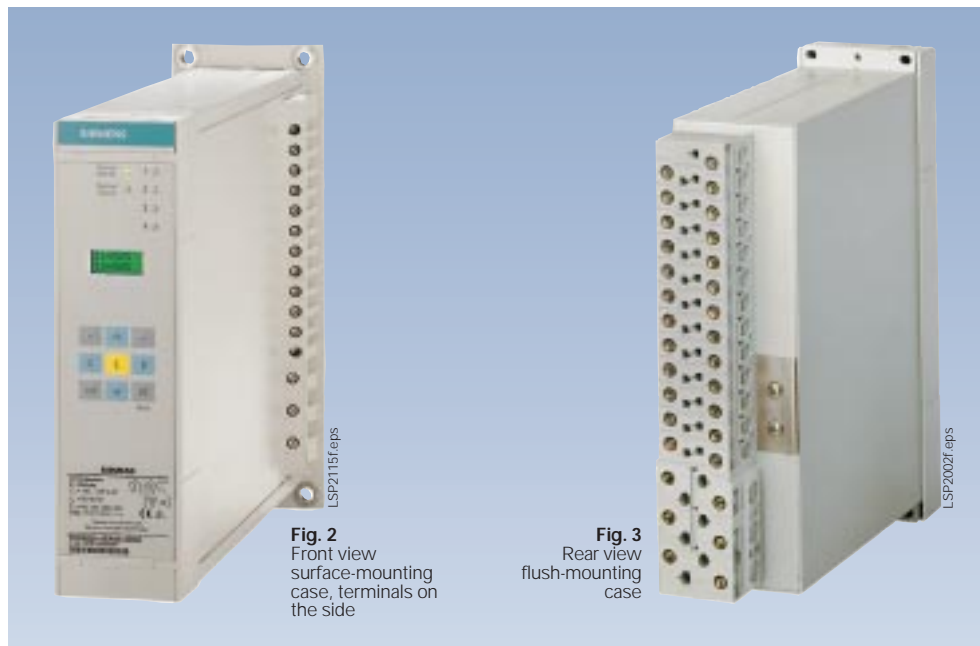
The 7SD60 unit is a numerical current differential protection relay, simple to set, operating in conjunction with the remote station via a two pilot-wire link.

It is connected to the primary current transformers via an external summation current transformer. The unit operates internally on the summated current taken from the secondary side of the summation current transformer. The link to the remote station is realized by means of a pair of symmetrical pilot-wires allowing distances of up to approximately 12 km. Adaptation to the pilot-wire resistance is effected by means of software within the unit. Therefore matching is not necessary.

The primary field of application of the unit is protection of short overhead lines and cables with two line ends. However, transformers and reactors may be located within the protection zone. The unit can be fitted with inrush restraint in such cases. A differential protection instantaneous tripping stage is also provided in this case. Vector group adaptation is not effected inside the unit and must, if necessary, be effected by means of a matching current transformer.

The 7SD60 can be fitted with a pilot-wire monitoring function. In addition to monitoring the pilot-wire link to the remote station, this also includes bidirectional circuit-breaker intertripping and a remote tripping command.

This unit substitutes the 7SD24 steady-state differential protection. However, direct interoperation with the 7SD24 is not possible. On replacement of a 7SD24, its external summation current transformer can be used as the input transformer for the 7SD60.



**Fig. 2**  
Front view  
surface-mounting  
case, terminals on  
the side

**Fig. 3**  
Rear view  
flush-mounting  
case

### Construction

The compact 7SD60 protection relay contains all the components for:

- Measured value acquisition and evaluation
- Operation and LCD indications
- Alarm and command contacts
- Input and evaluation of binary signals
- Data transmission via the RS485 bus interface
- Auxiliary voltage supply

The primary current transformers are connected to the 4AM49 summation transformer. At the rated current value of either 1 A or 5 A this outputs a current of 20 mA which is measured by the 7SD60 unit. The summation current transformer is supplied together with the protection unit if so ordered.

The unit can be supplied in two different housings. The one for flush mounting in a panel or cubicle has connection terminals at the rear. The version for panel surface mounting is supplied with terminals accessible from the front. Alternatively the unit can be supplied with two-tier terminals arranged above and below the unit.

### Functions

The following functions are integrated:

- Current differential protection with adjustable trip value  $I_{Diff>}$
- Differential protection with combined trip release ( $I_{Diff>}$  and  $I$ )
- Detection of current transformer saturation due to external faults. In consequence: Increased restraint of differential protection.
- Inrush restraint with instantaneous tripping stage
- Seal-in of the trip command until manual reset (Lockout function)
- Pilot-wire monitoring
- Circuit-breaker intertripping to the remote station
- Remote tripping command via a binary input

### Improved measuring methods

By means of digital measured value processing, in particular through use of numerical fundamental frequency filters, the interference effects of DC components in the instrument transformer circuits and other transient components in the differential current is practically filtered out. By that, use of sensitive settings of the protection unit is possible, even under difficult conditions.

Digital 100 Hz filters, which operate precisely and have no negative effect on the long-term stability, are employed for detection of the inrush condition.

### Continuous self-monitoring

Both the hardware and software of the unit are continuously self-monitored. High availability is thus ensured.

### Event-logging with time-stamp

The 7SD60 unit makes available extensive data for analysis of faults and for supervision of the operating conditions. The messages are time-stamped and stored in various memories.

- Fault indications (fault logs)  
The last three fault logs are always available on request. All the events associated with differential protection tripping are recorded on a millisecond time resolution. Whenever a new fault operation occurs, the oldest one stored is overwritten.
- Operational indications (event logs)  
All operational indications are stored in a circular buffer.

### Operational measured values

Two measured values can be displayed simultaneously on the LCD display. The following measured values are available for supervision and commissioning purposes:

- The summated current at the local relay (which is a replica of the symmetrical operating current of the line)
- The calculated summated current of the remote end
- The differential current of the line. This is the difference of the summated current of the local relay and the summated current of the remote end.
- Pilot-wire resistance (for commissioning and setting)
- The angle between the summated currents (for commissioning)
- Restraint current

### Testing aids

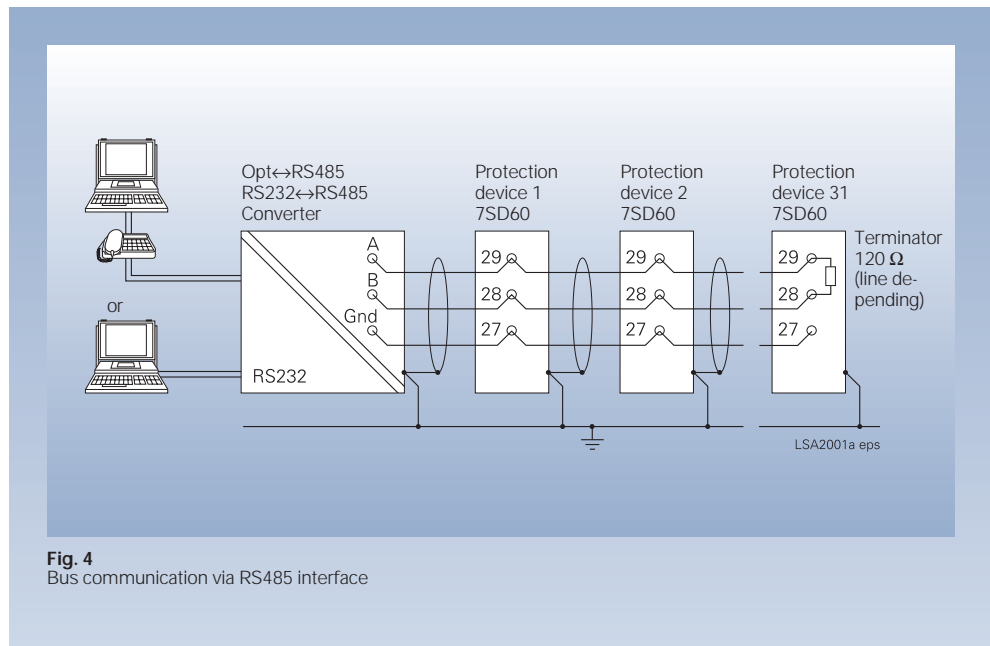
The protection unit facilitates testing and commissioning for the user. Numerous test functions, which can be activated either by means of the operator keys or by means of the DIGSI PC program, have been integrated in the unit. Entry of a password is required for some of the tests. The following testing aids are provided:

- Measured value display of the operational values
- Interrogation of the status of binary inputs, LEDs
- Circuit-breaker trip test  
Operation of the trip relay by means of operator keys. Previous entry of password necessary.

### Freely assignable inputs and outputs

A number of messages, e.g. blocking of a function via a binary input or the TRIP command (which is assigned to a command contact) are available within the unit. Commonly used messages are pre-assigned, so that normally there is no need to alter the inputs and outputs.

Nonetheless, provision has been made for "OR linking" by the user of up to 10 messages to a binary input. Up to 20 messages can be simultaneously assigned to a command and alarm relay or to a LED.



**Fig. 4**  
Bus communication via RS485 interface

### Serial data transmission

As standard, the unit is fitted with an RS485 interface. This is suitable for connection to a bus and allows connection of up to 32 devices via a two-wire serial interface (use of a third core for earth is recommended). A PC is connected via this interface using an RS232<->RS485 converter, thus allowing use of the DIGSI operator program, by means of which PC-aided planning, parameter setting and evaluation can be performed. By this readout it is also possible to output the fault recordings stored by the unit on occurrence of faults.

Using a RS485<->820 nm optical converter as an accessory (7XV5650, 7XV5651), it is possible to provide an interference-free and isolated link to a central control system or a remote control system employing DIGSI, thus allowing implementation of economically viable configurations, e.g. for remote diagnostics.

The serial interface can also be set in the IEC 60870-5-103 mode (VDEW - Association of German Utilities - interface), thus allowing integration of the unit in a station control system. However, only 2 messages (ready for operation and the trip signal) and the fault recording are available. For this reason use of the 7SD502 unit is recommended in those cases in which integration in the station control system is a prime consideration.

# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Description

### Easy setting

Menu-driven setting is carried out via the integrated operator panel and the LCD display. Setting by means of the DIGSI program is, however, much more user-friendly. In the latter case all the PC functions of the DIGSI standard program, which is common to all SIPROTEC units, are available. An economic version DIGSI-Light is available for the 7SD60, 7SJ60 and 7RW60 units.

### Fault recording

Fault recording is carried out on tripping by the differential relay. The instantaneous value of the summated current of the local relay and of the remote relay are recorded in addition to the differential current and the restraint current.

Triggering of fault recording from the PC is also possible for test purposes.

Up to eight faults in total can be saved at any one time. The oldest of these is overwritten whenever a new fault is recorded.

Total fault memory time is 5 s.

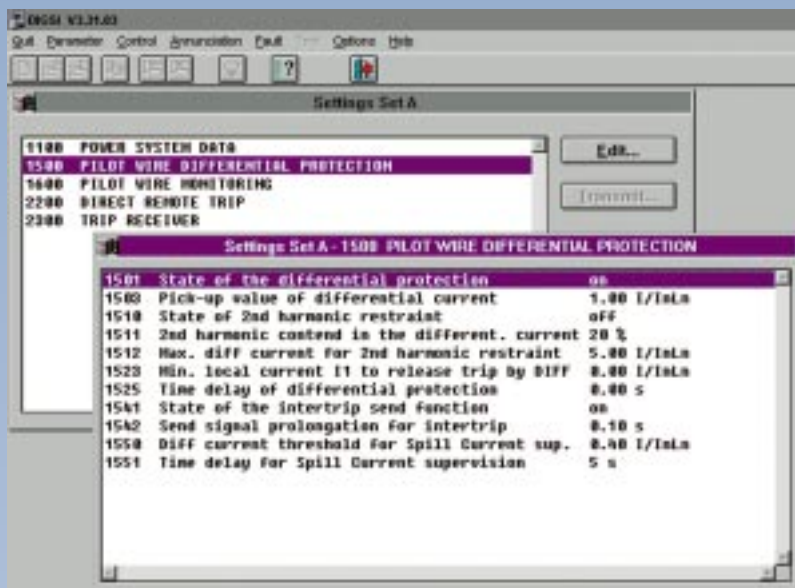


Fig. 5  
PC-based setting

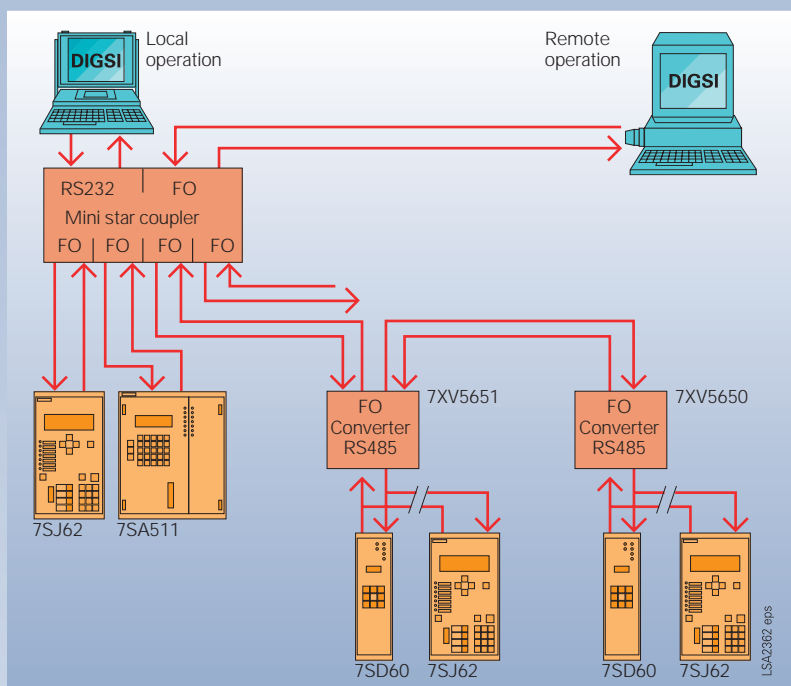


Fig. 6  
Central operation via DIGSI

## Functions

### Mode of operation of the differential protection relay

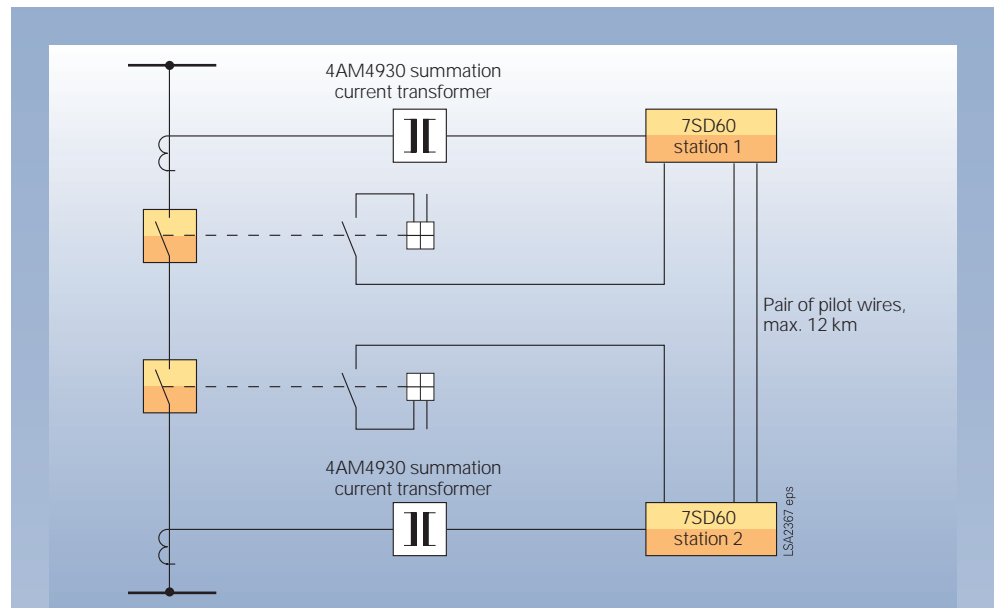
An external summation current transformer 4AM49, which can be supplied as an accessory either in a 1 A or a 5 A version, allows connection of any secondary currents of the primary current transformers (see Fig. 7). The standard ratios of the three primary windings of the summation current transformer are  $I_{L1}:I_{L2}:I_{L3} = 5:3:4$  ( $I_{L1}:I_{L3}:I_{L0} = 2:1:3$ ) (see Fig. 9). In consequence the sensitivity of the tripping characteristic for single-phase faults is appreciably higher in comparison to that for two-phase and three-phase faults. Since the current on such faults is often weak, an amplification factor of 1.7 to 2.8 referred to the symmetrical response value is achieved.

Other sensitivity values can, however, be obtained by altering the connections at the summation c.t.

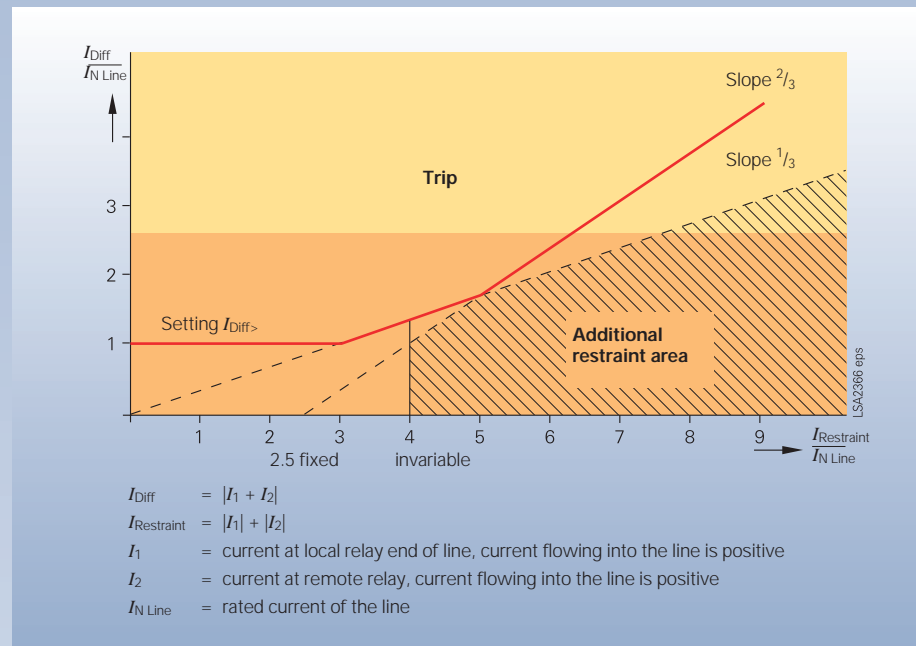
With a symmetrical three-phase current of  $1 \times I_{N, \text{Line}}$ , the secondary current of the summation current transformer is 20 mA.

The 7SD60 measures and digitalizes the summated current  $I_{M1}$  of the local relay by means of a sensitive current input (see Fig. 9). A voltage drop occurs across a fixed-value resistor  $R_b$  installed in the unit. With a through-flowing load or a through-flowing short-circuit current, the voltage drop at both ends of the line is approximately equal but of opposite polarity, so that no current flows through the pilot-wire. On occurrence of an internal fault, different values are obtained for the voltage drop across  $R_b$  at both ends. In consequence a current  $I_a$  flows through the pilot-wire, which is measured by means of the current transformer. In conjunction with the pilot-wire resistance (available as a parameter in the unit) and the internal resistor  $R_a$ , it is possible to calculate the differential current from the measured current flowing through the pilot-wire. As soon as an adjustable value is reached, the protection relay trips the line at both ends.

Matching of the sensitivity of the unit for different values of pilot-wire resistance is effected by the firmware of the unit during parameter setting,



**Fig. 7**  
7SD60 Line differential protection for operation with two pilot wires



**Fig. 8**  
Trip characteristic of differential protection

so that time-consuming matching of the pilot-wire resistance is unnecessary.

### Trip characteristic of the differential protection relay

The main function of the unit is current comparison protection. The trip characteristic is fixed and takes into account both the linear and the non-linear er-

rors of the current transformers. It is only necessary to set the tripping value  $I_{\text{Diff} >}$  (see Fig. 8), although the standard setting is suitable for most applications. It should be parameterized according to the rated current of the line; sensitive setting is possible even when the current transformer rated currents and the line

rated currents differ by as much as a factor of 2. Differences in the current transformation ratios at the ends of the line must, however, be compensated for by means of external matching current transformers.

In some cases this can be realized by the summation current transformer.

# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Functions

### Overcurrent release / differential current monitoring

The differential protection function can be combined with an additional overcurrent release. To this end the criteria „overcurrent“ and „differential current“ are linked logically so that a TRIP command is given out by the differential function only when a differential current and an overcurrent co-exist. By this means it is often possible to avoid malfunctioning due to pilot-wire short-circuit or wire-break of a connection between a current transformer and the summation current transformer. For this purpose the 7SD60 is fitted with an additional differential current monitoring function, which can effectively block the differential protection after a delay of some seconds on reaching of an adjustable value of differential current in conjunction with simultaneous operational current  $I_{M1}$  within the load range.

### Saturation detector

Improved stability on single-ended saturation of the primary current transformers is ensured by means of an integrated saturation detector. It provides additional stability during external faults. 5 ms are enough time to measure an external fault due to a high restraint and small differential current. Indication is done within the additional restraint area (see Fig. 8). If - due to c.t. saturation - the differential current flows into the trip area, the differential trip is blocked for a certain time. Transient saturation of current transformers caused by transposed DC components in the short-circuit current can thus be recognized. As a result the requirements on the current transformers are reduced so that they are only required to conduct the steady-state through-flowing short-circuit current without saturation.

### Pilot-wire link / pilot-wire monitoring

The link to the remote station comprises a symmetrical pair of wires (e.g. telephone lines). The maximum permissible distance between two stations is approximately 12 km. 4AM9513 isolation units can be employed for potential isolation against interference induced by longitudinal voltages where the pilot-wires run parallel to power cables over long distances.

Since the pilot-wires form an integral part of the differential protection, these are normally monitored continuously. This function is available as an option. To achieve this, 2 kHz pulses with a defined pulse-width ratio are transmitted to the remote relay via the pilot-wires. Detection of a fault in the pilot-wire link results in blocking of the differential protection.

### Circuit-breaker intertripping / remote tripping

Normally tripping is effected at both stations as a result of current comparison. Tripping at one end only can occur when an overcurrent release is used or with short-circuit currents only slightly above the tripping value. Circuit-breaker intertripping can be parameterized in the unit with integral pilot-wire monitor, so that definite tripping at both ends of the line is assured.

In addition, it is possible by means of a binary input to output a remote tripping command for both directions. The command transmission time is approximately 80 ms.

### Lockout of the TRIP command with manual reset

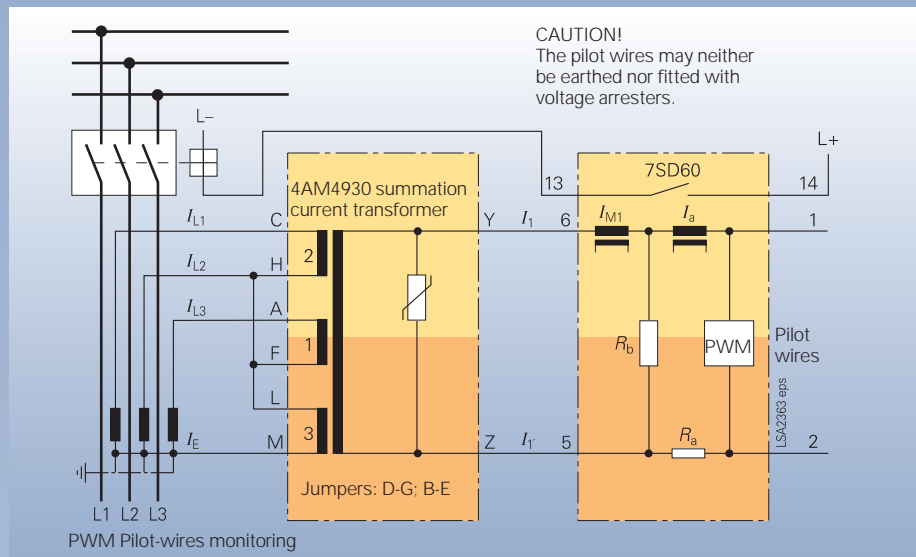
The TRIP command can be locked-out after tripping. In particular, in the case of transformers within the protection zone, reclosure of the line is normally effected only after the cause of the fault has been ascertained by the user. Manual reset is possible either via the operator panel (with password) or via a binary input. As a result premature reclosure of the circuit-breaker is prevented. The logic state of the TRIP command remains stored even during failure of the auxiliary supply voltage so that it is still present on restoration of the auxiliary supply voltage.

### Inrush restraint / instantaneous tripping stage

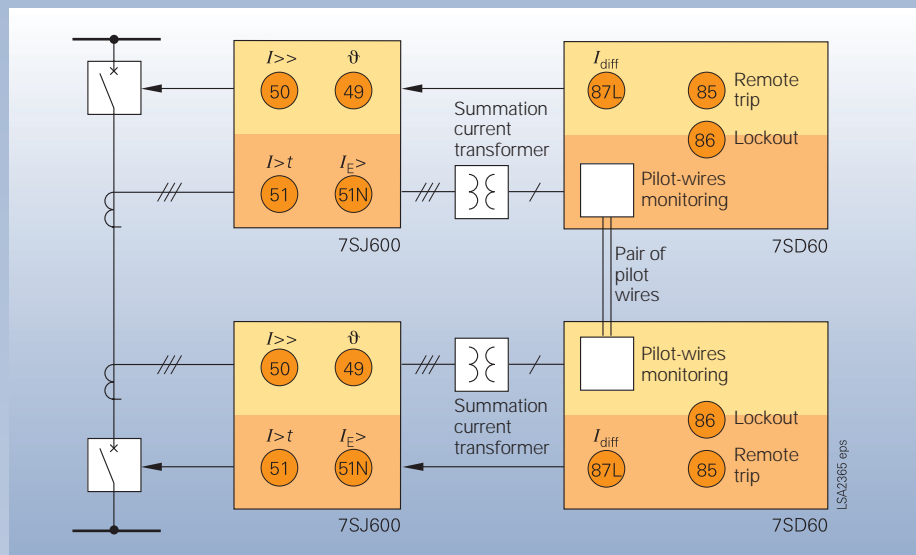
Where transformers or reactors are located within the protection zone, inrush restraint can be supplied as an option. This inrush restraint evaluates the second harmonic of the differential current, which is typical for inrush phenomena. If the second harmonic value of the differential current referred to the fundamental frequency exceeds a preset value, tripping by the differential protection is blocked. In the case of high-current internal faults, whose amplitude exceeds the inrush current peak, tripping can be carried out instantaneously.

Vector group adaptation is not effected inside the unit and must, where necessary, be brought about by means of an external matching transformer scheme.

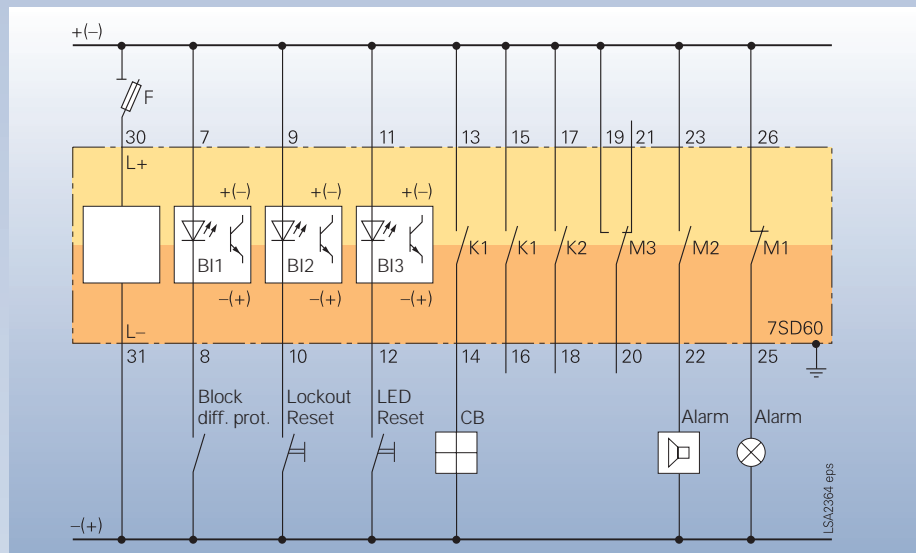
Connection examples



**Fig. 9**  
Standard connection L1-L3-E,  
suitable for all type of networks



**Fig. 10**  
Protection configuration with  
main (7SD60) and backup  
overcurrent (7SJ60) protection



**Fig. 11**  
Typical circuit for auxiliary  
voltage supply

# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Technical data

### Input circuits

Rated current $I_N$	20 mA without summation current transformer 1 or 5 A with summation current transformer
Rated frequency $f_N$	50/60 Hz parameterizable
Thermal overload capability current path continuous for 10s for 1s	$2 \times I_N$ $30 \times I_N$ $100 \times I_N$

### Auxiliary voltage

Auxiliary voltage via integrated DC/DC converter	
Rated auxiliary DC voltage/permissible variations	24/48 V DC /19 to 58 V DC 60/110/125 V DC /48 to 150 V DC 220/250 V DC /176 to 300 V DC
Superimposed AC voltage $V_{aux}$ Peak-to-peak	$\leq 12\%$ at rated voltage $\leq 6\%$ at limits of admissible voltage
Power consumption Quiescent Energized	Approx. 2 W Approx. 4 W
Bridging time during failure/ short-circuit of auxiliary voltage	$\geq 50$ ms (at $V_{aux} \geq 100$ V AC/DC) $\geq 20$ ms (at $V_{aux} \geq 24$ V DC)
Rated auxiliary voltage AC $V_{aux}$ /permissible variations	115 V AC / 88 to 133 V AC

### Command contacts

Number of relays	2 (marshallable)
Contacts per relay	2 NO or 1 NO
Switching capacity Make Break	1000 W/VA 30 W/VA
Switching voltage	250 V
Permissible current Continuous For 0.5 s	5 A 30 A

### Signal contacts

Number of relays	3 (2 marshallable)
Contacts per relay	1 CO
Switching capacity Make Break	1000 W/VA 30 W/VA
Switching voltage	250 V AC/DC
Permissible current	5 A

### Binary inputs

Number	3 (marshallable)
Operation voltage	24 to 250 V DC
Current consumption, energized,	Approx. 2.5 mA independent of operating voltage
Pick-up threshold, reconnectable	by solder bridges
Rated aux. voltages 24/48/60 V DC $V_{pick-up}$ $V_{drop-off}$	$\geq 17$ V DC < 8 V DC
Rated aux. voltages 110/125/220/250 V DC $V_{pick-up}$ $V_{drop-off}$	$\geq 74$ V DC < 45 V DC

### Serial interface (Isolated)

Standard	RS485
Test voltage	2.8 kV DC for 1 min
Connections	Via wire to housing terminals, 2 data transmission lines, 1 earthing cable for connection to an RS485↔RS232 converter, cables have to be shielded, screen has to be earthed Setting at supply: 9600 baud
Transmission speed	min. 1200 baud; max. 19200 baud

### Construction

Housing 7XP20	For dimensions, see dimension drawings
Dimensions	see Fig. 13
Weight With housing for surface mounting With housing for surface mounting/cubicle mounting	approx. 4.5 kg approx. 4 kg
Degree of protection acc. to EN 60529 Housing Terminals	IP 51 IP 21

**CE-conformity, standards**

This product is in conformity with the directives of the Council of the European Communities on the approximation of the laws of the Member States relating to the electromagnetic compatibility (EMC Council Directive 89/336/EEC) and concerning electrical equipment for use within specified voltage limits (low-voltage directive 73/23/EEC). The product conforms with the international standard IEC 60255 and the national standard DIN 57 435 Part 303 (corresponding to VDE 0435 Part 303).

The unit has been developed and manufactured for use in industrial areas in accordance with the EMC standard.

Conformity is proved by tests performed by Siemens AG in line with article 10 of the Council Directives in accordance with the generic standards EN 50081 and EN 50082 for the EMC directive and standard EN 60255-6 for the low-voltage directive.

**Insulation tests****Standards**

IEC 60255-5 ANSI/IEEE C37.90.0

**Voltage test (routine test)**

All circuits except DC supply and RS485  
Only DC voltage supply and RS485

2 kV (rms), 50 Hz  
2.8 kV DC**Impulse voltage test (type test)**

All circuits, class III

5 kV (peak), 1.2/50  $\mu$ s, 0.5 J; 3 positive and 3 negative shots at intervals of 5 s**Test crosswise:**

Measurement circuits, pilot wire connections,  
power supply, binary inputs, class III, (no tests cross-  
wise over open contacts, RS458 interface terminals)

**EMC-tests;  
Immunity  
(type tests)****Standards**

IEC 60255-6; IEC 60255-22 (international product standard) EN 50082-2 (generic standard) VDE 0435 Part 303 (German product standard)

**High-frequency test**

IEC 60255-22-1, VDE 0435 Part 303; class III

2.5 kV (peak); 1 MHz;  $\tau = 15$  ms;  
400 shots/s; duration 2 s**Electrostatic discharge**

IEC 60255-22-2, EN 61000-4-2; class III

4/6 kV contact discharge;  
8 kV air discharge; both polarities; 150 pF;  
 $R_f = 330 \Omega$ **Radio-frequency electromagnetic field,**

non-modulated report IEC 60255-22-3 class III

10 V/m 27 to 500 MHz

**Radio-frequency electromagnetic field, amplitude-**

modulated IEC 61000-4-3; class III

10 V/m 80 to 1000 MHz; AM 80 %; 1 kHz

**Radio-frequency electromagnetic field, pulse-**

modulated IEC 61000-4-3/ENV 50204; class III

10 V/m, 900 MHz; repetition rate 200 Hz,  
duty cycle 50 %**Fast transients/bursts**

IEC 60255-22-3, IEC 61000-4-4, class IV

2 kV; 5/50 ns; 5 kHz; burst length = 15 ms;  
repetition rate 300 ms; both polarities;  
 $R_f = 50 \Omega$ ; duration 1 min**Conducted disturbances induced by radio-**

frequency fields, amplitude-modulated

IEC 61000-4-6, class III

10 V; 150 kHz to 80 MHz; AM 80 %; 1 kHz

**Power frequency magnetic field**

IEC 61000-4-8; class IV; EN 60255-6

30 A/m; 50 Hz, continuous  
300 A/m for 3 s; 50 Hz; 0.5 mT, 50 Hz**Oscillatory surge withstand capability**

ANSI/IEEE C37.90.1 (common mode)

2.5 to 3 kV (peak), 1 MHz to 1.5 MHz  
decaying oscillation; 50 shots per s;  
duration 2 s;  $R_f = 150 \Omega$  to 200  $\Omega$ **Fast transient surge withstand capability**

ANSI/IEEE C37.90.1 (common mode)

4 to 5 kV; 10/150 ns; 50 shots per s  
both polarities; duration 2 s;  $R_f = 80 \Omega$ **Radiated electromagnetic interference**

ANSI/IEEE C37.90.2

10 to 20 V/m; 25 to 1000 MHz;  
amplitude and pulse modulated**High-frequency test**

Document 17C (SEC) 102

2.5 kV (peak, alternating polarity)  
100 kHz, 1 MHz, 10 and 50 MHz,  
decaying oscillation;  $R_f = 50 \Omega$ **EMC-tests; emission  
(type tests)****Standard**

EN 50081- (generic standard)

**Conducted interference voltage, auxiliary**

voltage only, EN 55022, VDE 0878 Part 22

CISPR 22, limit value class B

150 kHz to 30 MHz

**Interference field strength**EN 55011, VDE 0875 Part 11,  
IEC CISPR 11, limit value class A

30 to 1000 MHz

# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Technical data (continued)

### Vibration and shock stress during operation

Standards	IEC 60255-21; IEC 60068-2
Vibration IEC 60255-21-1, class I IEC 60068-2-6	sinusoidal 10 to 60 Hz; $\pm 0.035$ mm amplitude; 60 to 150 Hz; 0.5 g acceleration; sweep rate 1 octave/min; 20 cycles in 3 orthogonal axes
Shock IEC 60255-21-2, class I	half sine 5 g acceleration, duration 11 ms, 3 shocks in each direction of 3 orthogonal axes
Seismic vibration IEC 60255-21-3, class I IEC 60068-2-6	sinusoidal 1 to 8 Hz; $\pm 3.5$ mm amplitude (horizontal axis) 1 to 8 Hz; $\pm 1.5$ mm amplitude (vertical axis) 8 to 35 Hz; 1 g acceleration (horizontal axis) 8 to 35 Hz; 0.5 g acceleration (vertical axis) sweep rate 1 octave/min 1 cycles in 3 orthogonal axes

### during transport

Standards	IEC 60255-21; IEC 60068-2
Vibration IEC 60255-21-1, class II IEC 60068-2-6	sinusoidal 5 Hz to 8 Hz: $\pm 7.5$ mm amplitude 8 Hz to 150 Hz: 2 g acceleration sweep rate 1 octave/min 20 cycles in 3 orthogonal axes
Shock IEC 60255-21-2, class I IEC 60068-2-27	half sine acceleration 15 g, duration 11 ms, 3 shocks shocks in each direction of 3 orthogonal axes
Continuous shock IEC 60255-21-2, class I IEC 60068-2-29	half sine acceleration 10 g, duration 16 ms, 1000 shocks in each direction of 3 orthogonal axes

### Climatic stress

EN 60255-6  
IEC 60255-6  
DIN VDE 0435 Part 303

Recommended temperature	-5 to +55 °C ( $>55$ °C/131 °F decreased display contrast)
Limit temperature during service during storage during transport (Storage and transport with standard works packing!)	-20 to +70 °C -25 to +55 °C -25 to +70 °C
Humidity during service	mean value per year $\leq 75$ % relative humidity, on 30 days a year up to 95 % relative humidity, condensation not permissible!
We recommend arrange the in such a way that they are kept from direct sun and from changes in temperature that might reduce condensation.	

### Line differential protection

All current values refer to the symmetrical current using standard connection.

Setting ranges Current threshold $I_1$ (release by local station current) Differential current Delay time $t$	$I/I_{N \text{ Line}}$ : 0 to 1.5 (step 0.01) $I/I_{N \text{ Line}}$ : 0.5 to 2.5 (step 0.01) 0 to 60 s (step 0.01 s)
Restraint by 2 <sup>nd</sup> harmonic (see Fig. 8) $2f_N/f_N$ Reset ratio	10 to 80 % approx. 0.7 – response value ( $I_{\text{Restraint}} = 0$ )
Inherent delays TRIP time for two-ended supply at 4 x set value	approx. 20 to 28 ms without restraint by 2nd harmonic approx. 32 to 42 ms with restraint by 2nd harmonic
Release time	approx. 35 ms
Tolerances at preset values under reference conditions Local station current threshold Differential current	$\pm 3$ % of setpoint, min. 0.02 x $I_N$ $\pm 5$ % of setpoint, min. 0.02 x $I_N$
Influence parameters Auxiliary supply voltage $0.8 \leq V_{\text{aux}}/V_{\text{auxN}} \leq 1.15$ Temperature in range $0 \text{ °C} \leq \theta_{\text{amb}} \leq 40 \text{ °C}$ Frequency in range $0.9 \leq f/f_N \leq 1.1$	$\leq 1$ % $\leq 1$ %/10 K $\leq 4$ %
Pilot wires Number	2 Symmetric telephone pairs are recommended with loop resistance 73 $\Omega$ /km and capacitance 60 nF/km
Core-to-core asymmetry at 800 Hz Maximum loop resistance	max. $10^{-3}$ 1200 $\Omega$
Permissible induced longitudinal voltages on direct connection of the pilot wires  for connection via isolating transformer	$\leq 1.2$ kV, however, max. 60 % of the test voltage of the pilot wires $\geq 1.2$ kV, however, max. 60 % of the test voltage of the pilot wires and max. 60 % of the test voltage of the isolating transformers
Pilot-wire monitoring and intertripping (optional) Monitoring signal Alarm signal delay Inherent delay time of intertripping Extension of the intertripping signal	2000 Hz, pulse-code modulation 1 to 60 s (step 1 s) approx. 65 ms 0 to 5 s (step 0.01 s)

### Remote trip

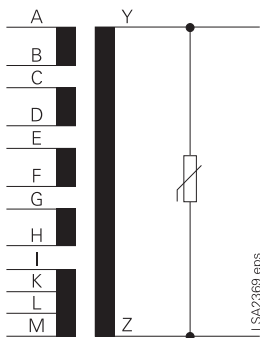
Tripping of the remote end circuit-breaker for units with pilot-wire monitoring only

### Lockout function

### Additional functions

Setting ranges		
Prolongation time for transmission to remote station		0 to 60 s (step 0.01 s)
Delay time for reception from the remote station		0 to 60 s (step 0.01 s)
Prolongation time for reception from the remote station		0 to 60 s (step 0.01 s)
Tolerances		
Delay time / release delay		1 % and 10 ms respectively
Inherent delay		
Transmission time without delay		approx. 80 ms
Lockout-seal-in of trip command		for differential protection and remote trip until reset
Lockout reset		by means of binary input and/or local operator panel/DIGSI
Operational measured values		
Operational currents		$I_1, I_2, I_{Diff}, I_{Restraint}$
Measurement range		0 to 240 % $I_N$
Tolerance ( $I_1$ )		3 % of rated value or of measured value
Fault event recording		Storage of the events relating to the last 8 faults
Time-tagging		
Resolution for operational events		1 s
Resolution for fault events		1 ms
Fault recording (max. 8 faults)		
Storage time (from response or trip command)		total of 5 s max., pre- and posttrigger time settable
Maximum length per recording	$T_{max}$	0.30 to 5.00 s (step 0.01 s)
Pre-event time	$T_{pre}$	0.05 to 0.50 s (step 0.01 s)
Post-event time	$T_{post}$	0.05 to 0.50 s (step 0.01 s)
Time resolution at 50 Hz		1 instantaneous value per 1.66 ms
Time resolution at 60 Hz		1 instantaneous value per 1.38 ms
Circuit-breaker test		Using test circuit

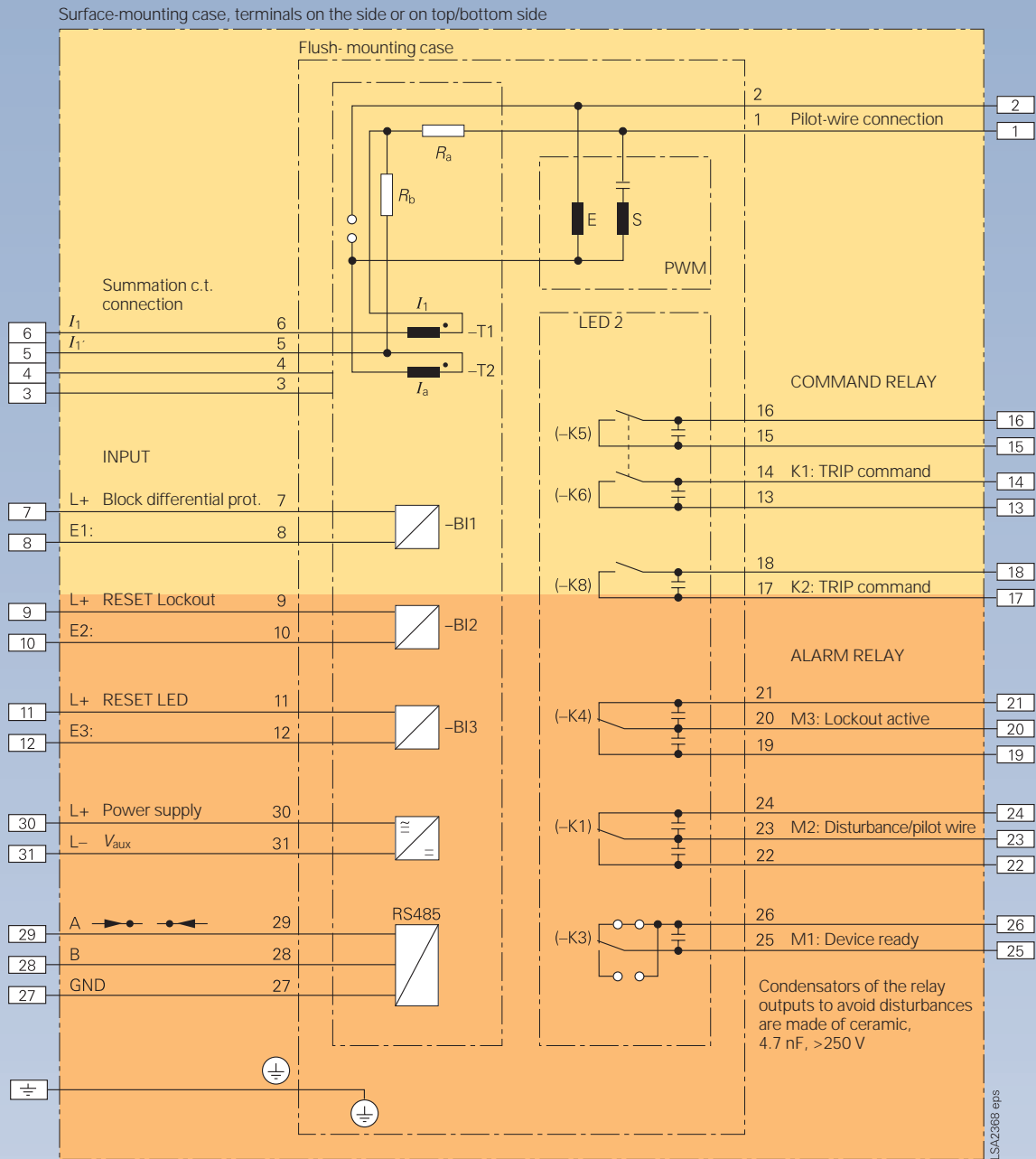
### 4AM4930 summation current transformer



Power consumption in the circuit with standard connection L1-L3-E (Fig. 9) referred to the through-flowing rated current (7SD600 unit in operation).				
$I_N$		in phase (approx. VA)		
		L1	L2	L3
1 A	Single-phase	2.2	1.3	1.7
	Symmetrical three-phase	0.6	0.2	0.35
5 A	Single-phase	3.5	1.5	2.2
	Symmetrical three-phase	0.7	0.2	0.5
Connections		4AM4930-7DB	4AM4930-6DB	
C.t. rated current		$I_N = 1$ A	$I_N = 5$ A	
Number of turns				
Primary windings				
	A to B	5	1	
	C to D	10	2	
	E to F	15	3	
	G to H	30	6	
	I to K	30	6	
	K to L	30	6	
	L to M	60	12	
Secondary windings		Y to Z	1736	
Thermal rating				
Continuous current in Amperes				
	A to B	4.5	20	
	C to D	4.5	20	
	E to F	4.5	20	
	G to H	4.5	20	
	I to K	1.2	6.5	
	K to L	1.2	6.5	
	L to M	1.2	6.5	
	Y to Z	0.2	0.2	
Secondary rated current with standard connection (see Fig. 9) and symmetrical 3-phase current		Y to Z	20 mA	
Requirements for the current transformers (c.t.)				
		$k_{alf1}$ and $k_{alf2} \geq \frac{I_{K, max}}{I_{N, c.t.}}, \frac{3}{4} \leq \frac{k_{alf1}}{k_{alf2}} \leq \frac{4}{3}$		
	$k_{alf1}$	accuracy limiting factor side 1		
	$k_{alf2}$	accuracy limiting factor side 2		
	$I_{K, max}$	through-flowing short-circuit current, max.		
	$I_{N, c.t.}$	primary transformer current		



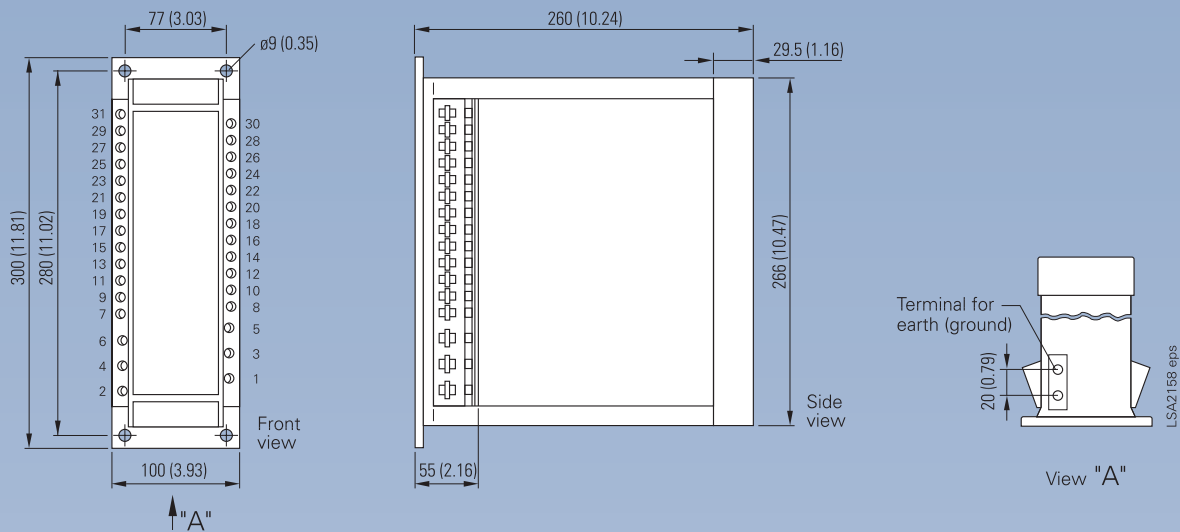
# Circuit diagram



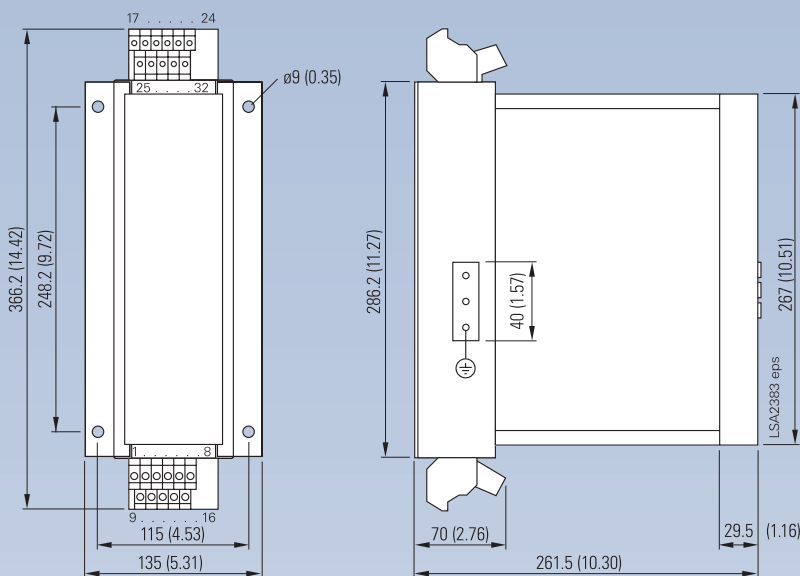
**Fig. 12**  
Connection diagram of the 7SD60 current differential protection

# SIPROTEC 7SD60 Numerical Current Differential Protection Relay for Two Pilot-Wire Link

## Dimension drawings

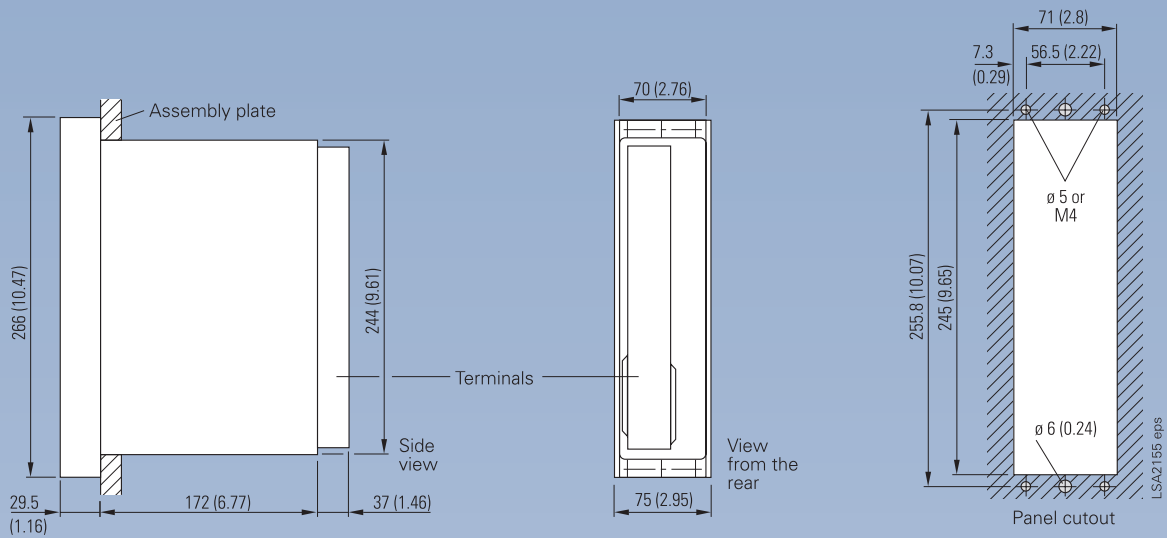


**Fig. 13**  
7SD60 with 7XP20 housing  
for panel surface-mounting,  
terminals on the side



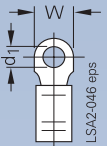
**Fig. 14**  
7SD60 with 7XP20 housing  
for panel surface-mounting  
terminals on top and bottom

Dimensions are indicated in mm;  
values stated in brackets are inches



**Fig. 15**  
7SD60 with 7XP20 housing  
for panel flush-mounting / cubicle-mounting  
terminals on the rear

## Terminals

	Wire size	Fittings (small items)	Order No. (manufacturer)	Order No. (Siemens)
 <p><b>Voltage contacts 7 to 31</b> Ring-cable lugs <math>d_1 = 4 \text{ mm (0.2 in)}</math> <math>W_{\text{max.}} = 9 \text{ mm (0.36 in)}</math> Wire size 1 to <math>2.6 \text{ mm}^2</math> (AWG 16 to 14)</p>	Crimp springs contacts <sup>1)</sup> from Weidmüller			
	0.5 to $1 \text{ mm}^2$	3000 units	162 552	W73073-A2502-C1
	1.5 to $2.5 \text{ mm}^2$	2500 units	162 550	W73073-A2503-C1

1) for panel flush-mounting only

Dimensions are indicated in mm;  
values stated in brackets are inches

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